

## BCS TUBULAR MOTOR - BUILD-IN RECEIVER AND ELECTRONIC LIMIT SETTING

#### **TECHNICAL SPECIFICATION:**

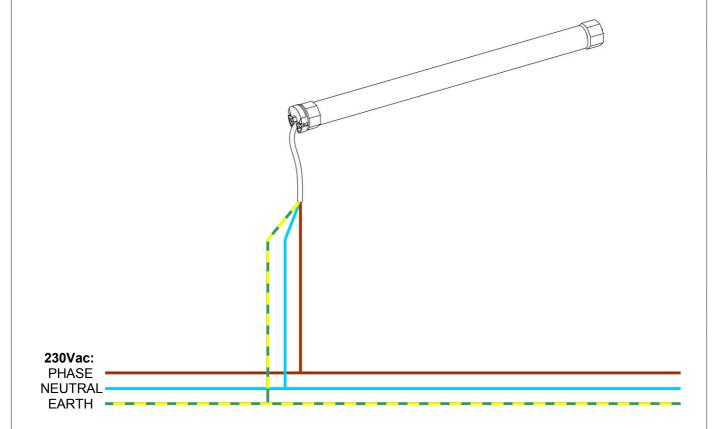
- 3416600099 6Nm, 33rpm, build-in receiver, electronic limit setting (110V)
- 3416600110 3Nm, 28rpm, build-in receiver, mechanical limit setting (230V)
- 3416600112 6Nm, 28rpm, build-in receiver, electronic limit setting (230V)
- 3416600116 13Nm, 14rpm, build-in receiver, electronic limit setting (230V)
- max. running time 4 min.
- protection degree IP44 (230V), class B (110V)
- has to be used with Multi remote and/or Multi wall switch RF

#### **IMPORTANT**



230V: use only wires BROWN (phase), BLUE (neutral) and GREEN/YELLOW (earth). The additional two wires are for connecting the optional obstruction sensor. Make sure these two wires do NOT make contact with power or connect together.

110V: use only wires BLACK (phase), WHITE (neutral) and GREEN (earth).





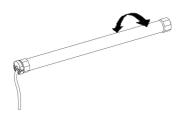
# BCS TUBULAR MOTOR - BUILD-IN MULTI RECEIVER AND ELECTRONIC LIMIT SETTING

## PROGRAMMING REMOTE / WALL SWITCH TO TUBULAR MOTOR

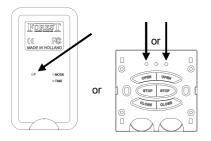
(button presses within 6 seconds)

first select the desired channel

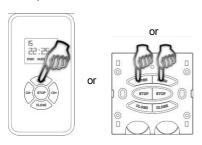
press button on motor, motor will turn short to acknowledge



#### press button two times



press OPEN-button one time



motor will turn to acknowledge

To change the direction of rotation, keep green button on motor pressed for 7 sec, until motor turns to acknowledge.

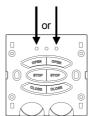
## ADD MORE REMOTES / WALL SWITCHES TO TUBULAR MOTOR

(button presses within 6 seconds)

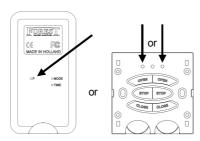
first select the desired channel

1st remote: press button two times





2nd remote: press button one time



motor will turn to acknowledge

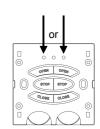
to add another channel on the same remote: select the programmed channel, press button on back of remote 2 times, select desired channel and press button on the back. Motor will turn to acknowledge.

## CANCEL ALL REMOTES OR OR WALL SWITCHES

(button presses within 6 seconds)

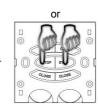
#### press button one time





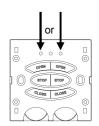
#### press STOP button one time





#### press button one time





motor will turn to acknowledge

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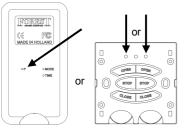
## BCS TUBULAR MOTOR WITH BUILD-IN RECEIVER AND ELECTRONIC LIMIT SETTING

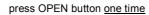
#### ADJUSTING UPPER AND LOWER END LIMITS:

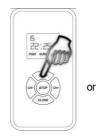


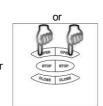
IMPORTANT: when more motors are programmed to one channel, end limits of all motors will be adjusted

press button one time

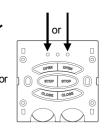






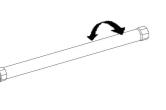






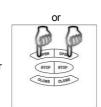
press button one time

motor will turn to acknowledge



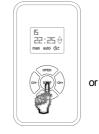
adjust UP limit





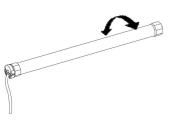


press STOP button when required height is reached. Press STOP button <u>5 times for 1 seconds</u> to confirm



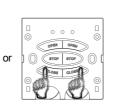


motor will turn to acknowledge

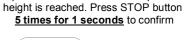


adjust DOWN limit

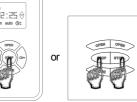




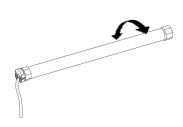




press STOP button when required



motor will turn to acknowledge, limits has been set successfully.



**FOREST** 



### **BCS TUBULAR MOTOR** WITH BUILD-IN RECEIVER AND ELECTRONIC LIMIT SETTING

#### **CANCELLATION OF UPPER AND LOWER END LIMITS:**



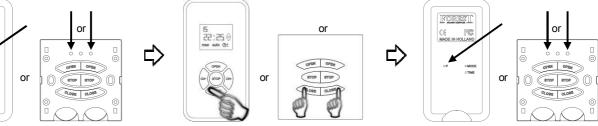
IMPORTANT: When cancelling end limits, all motors programmed to that channel will be cancelled

press button one time

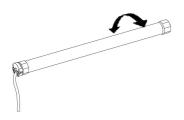


press CLOSE button one time

press button one time



motor will turn to acknowledge, limits has been set successfully.



### **REVERSE DIRECTION SETTING:**

When motor is  $\underline{not}$  running, press button on motor for  $\sim 7$  seconds, until motor turns to acknowledge.